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Neutron Imaging

A basic and recent text on neutron imaging: 50th IFF Spring School “Scattering! Soft, Functional and Quantum Materials” (Forschungszentrum Jülich 2019)

Download here:

https://www.fz-juelich.de/pgi/EN/Leistungen/SchoolsAndCourses/SpringSchool/History/SpringSchool2020/Lecture-Notes/_node.html

Motivation



This module's important concepts



- Instrumentation
- Radiography
- Tomography
- In operando
- Virtual Imaging experiment



Image and contrast formation

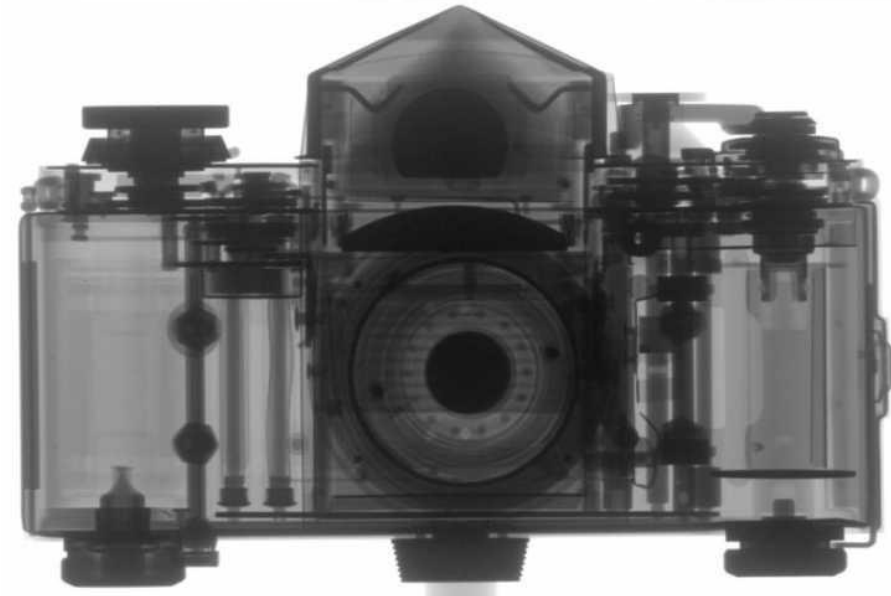
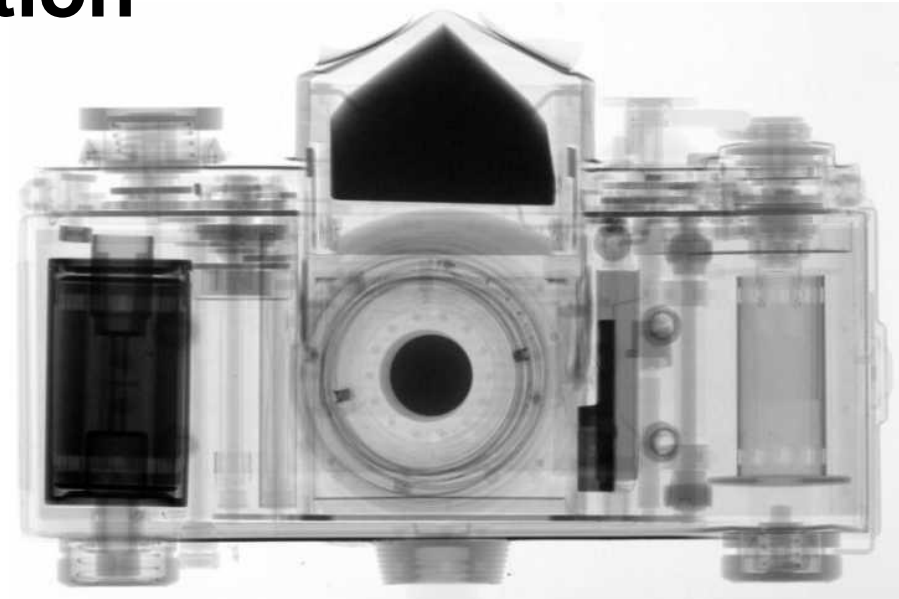
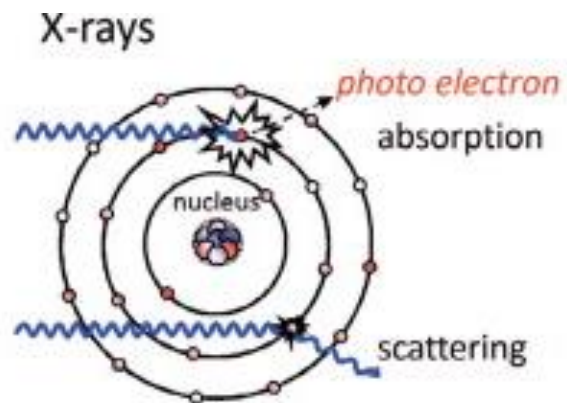
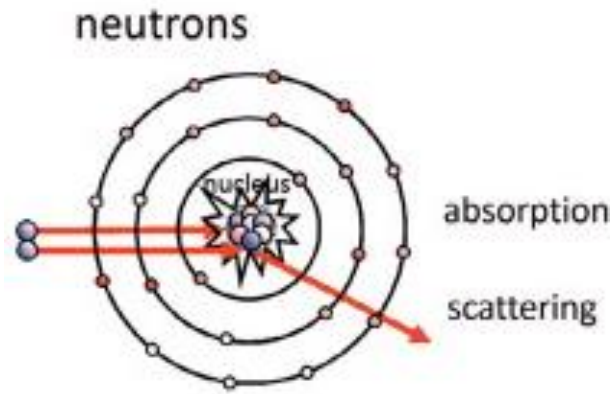
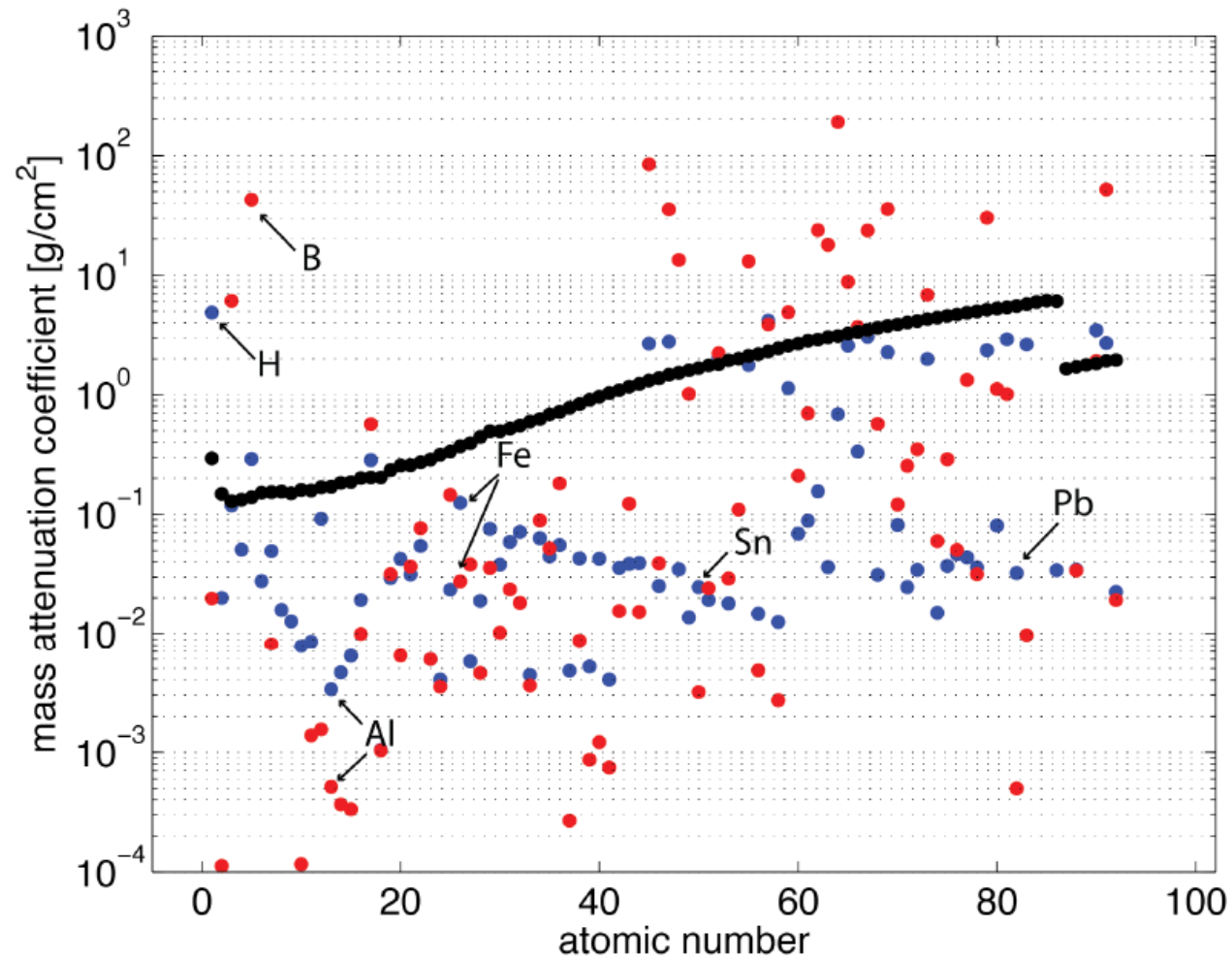
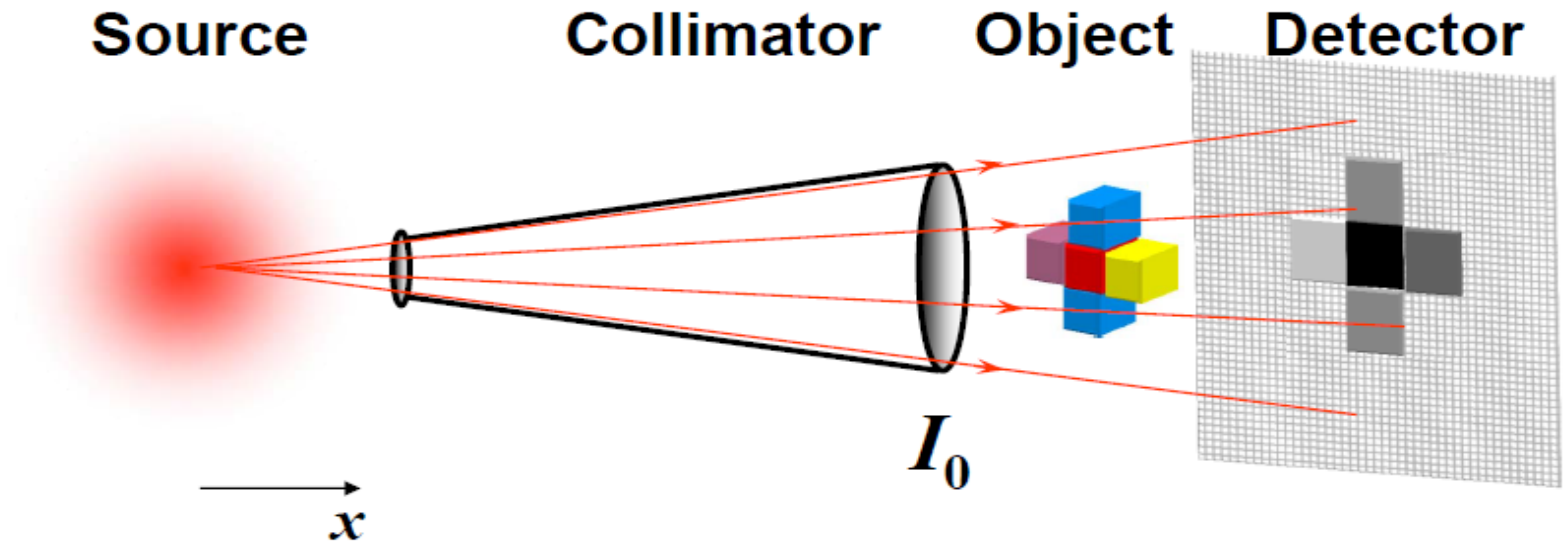


Image and contrast formation



$$\frac{\mu}{\rho} = \frac{N_a}{M} \sigma$$

Radiography



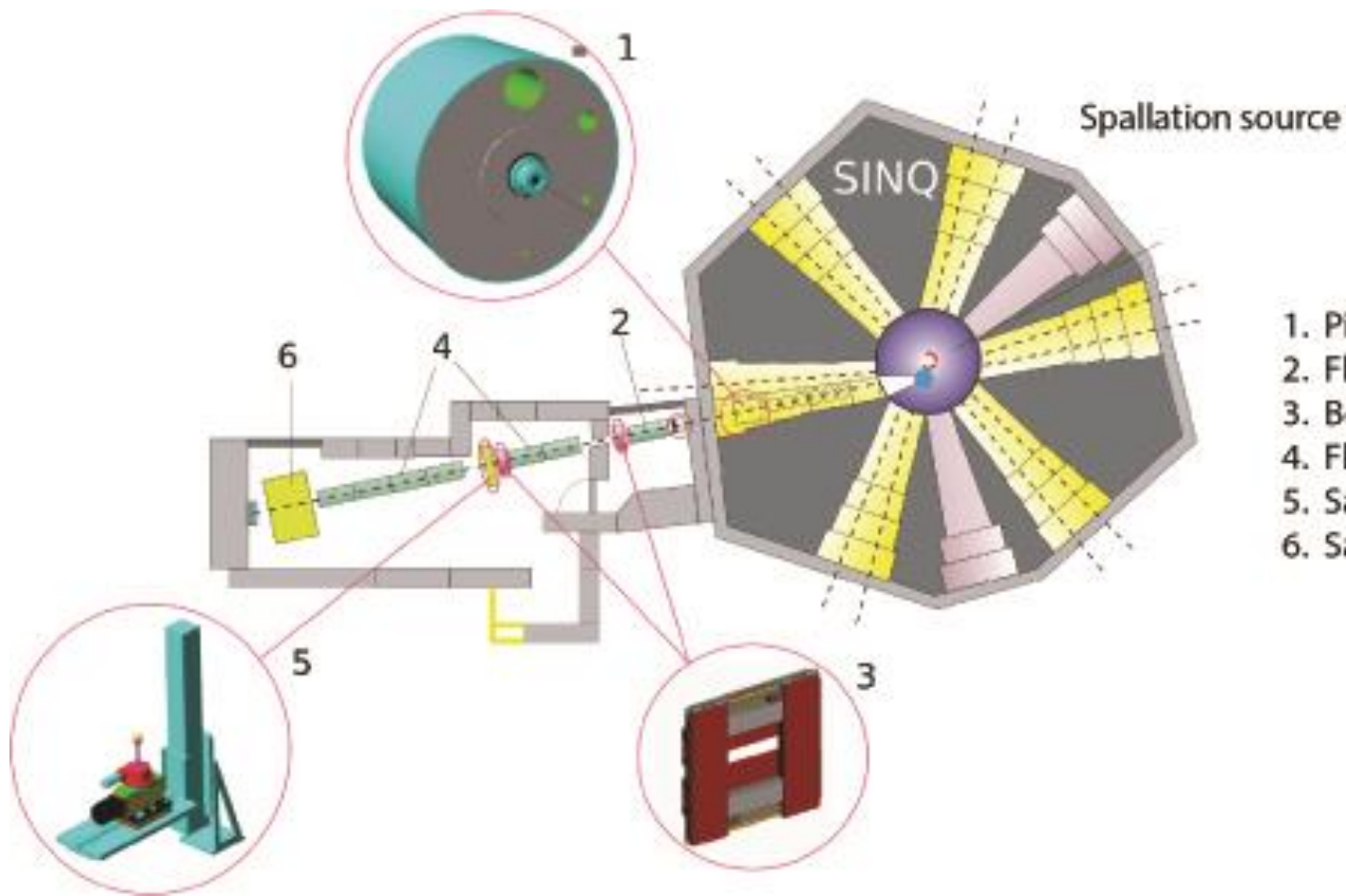
Beer-Lambert law: $\sim I_0 e^{-\int \mu(x) dx}$

x – propagation direction

I_0 – primary beam
 $\mu(x)$ – attenuation coefficient

$$\mu_{\text{total}} = \mu_a + \mu_s$$

Setup: ICON @ PSI

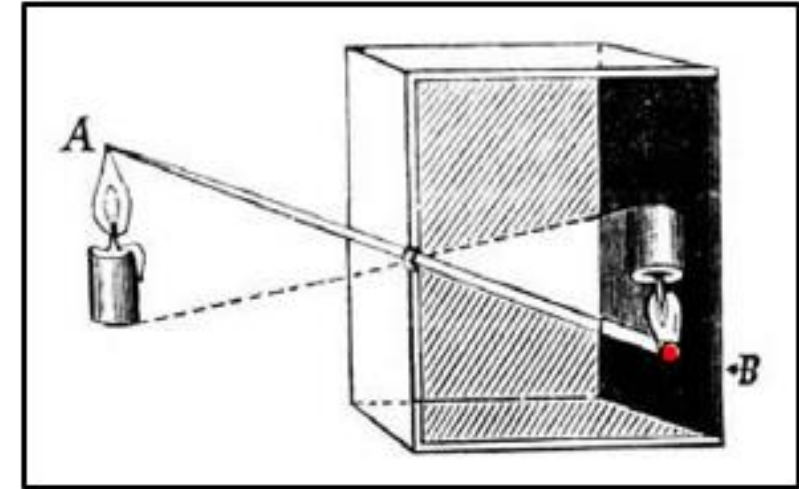
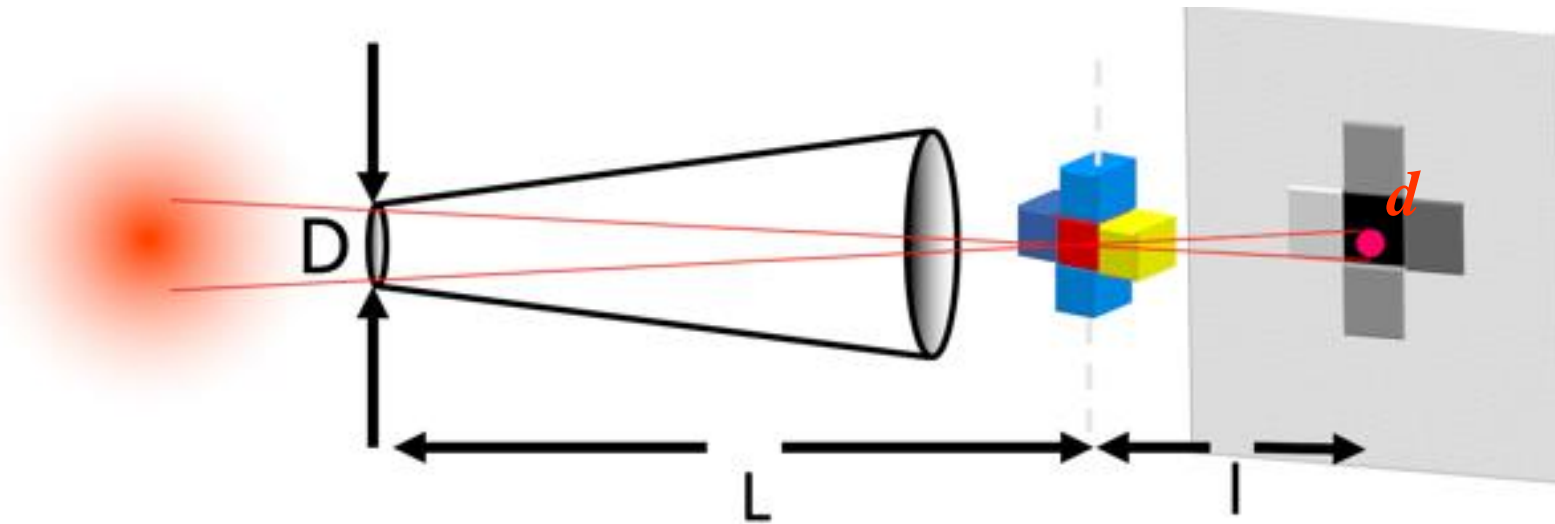


Spatial resolution

Source Collimator

Object Detector

Camera obscura



D – Collimator aperture, pinhole

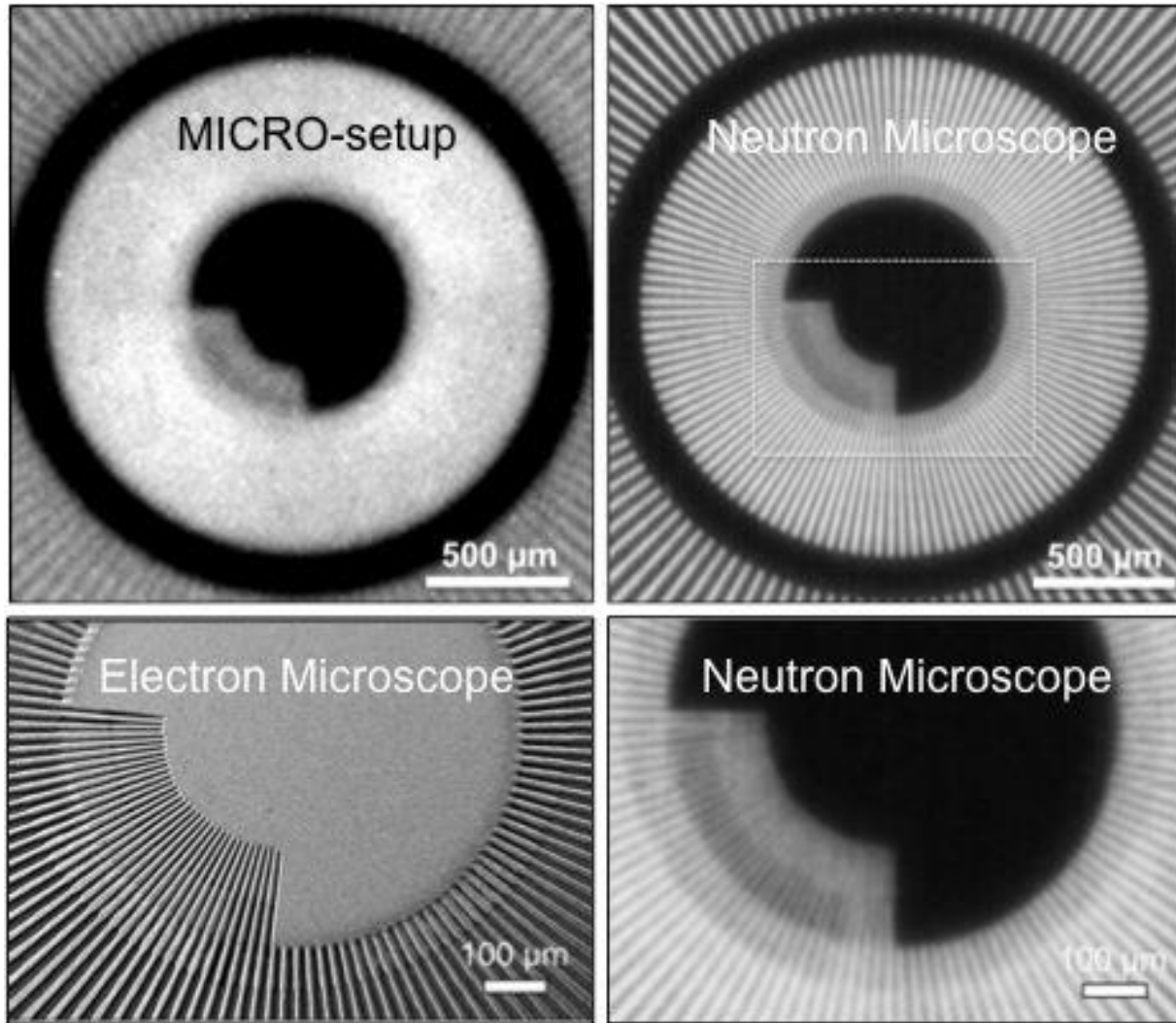
L – Distance Collimator-Object

l – Distance Object-Detector

$$d = \frac{l}{L/D}$$

Spatial resolution - Siemens star

32.9 μm

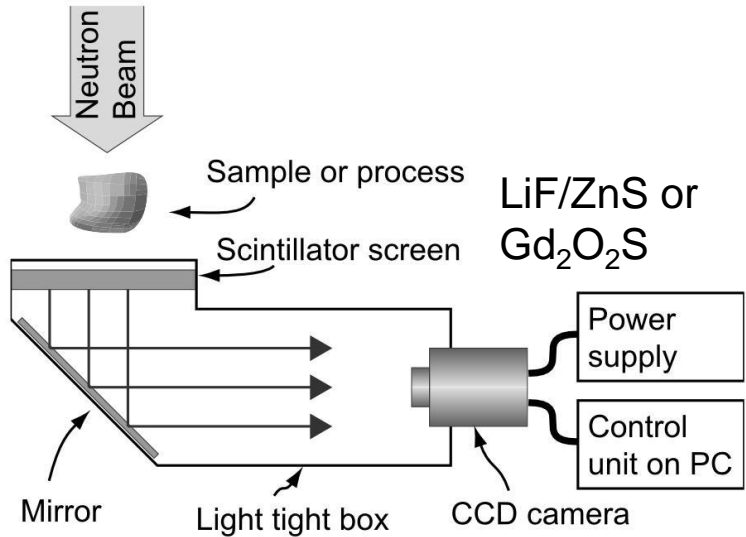


7.6 μm

Trtik, P. et al. (2015). *Physics Procedia*. **69**, 169.

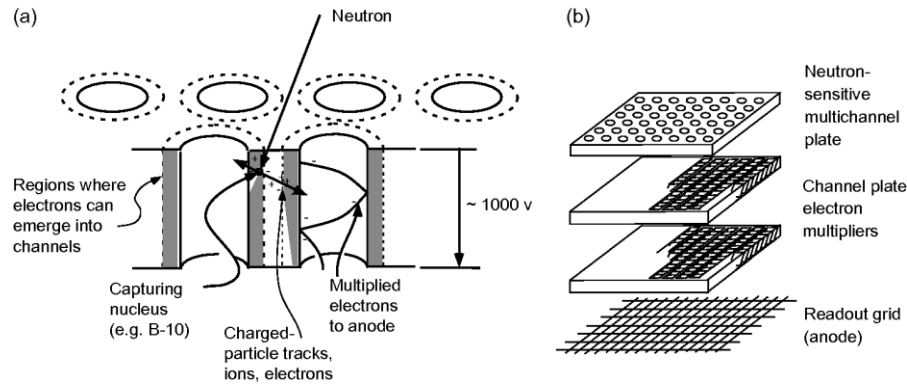
Detectors

Charged Coupled Device

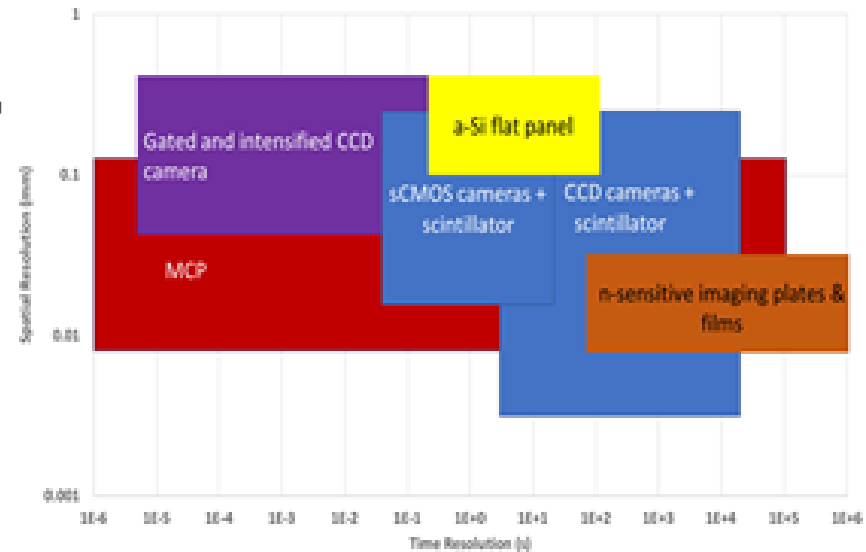
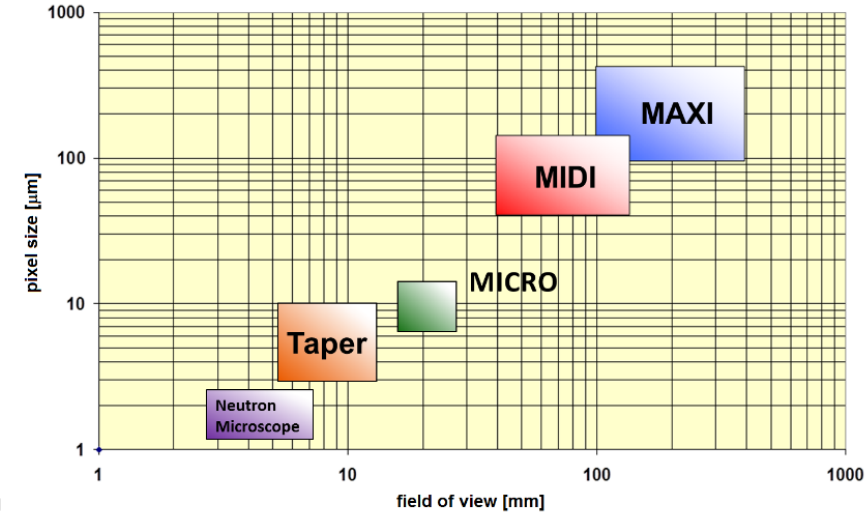


FOV: 0.5x0.5 m² to 5x5 mm²
 Pixelsize: 500x500 μm² to 1.5x1.5 μm²

Multi Channel Plate



<http://www.novascientific.com/technology/>

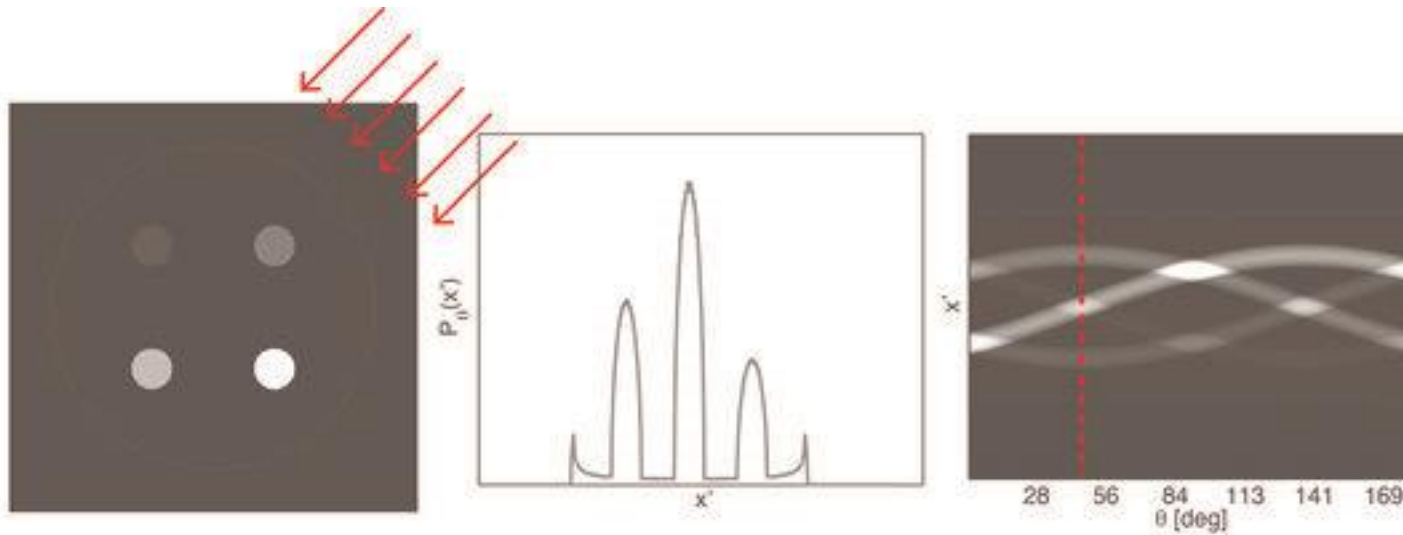


Principle for data acquisition in imaging experiment

1. Raw image, I_θ
2. Dark field image (no beam), correct for dark-current in detector system, DF
3. Flat-field image (open beam), correct for inhomogeneities in beam-profile and in detector screen, FF
4. Image, T_θ

$$T_\theta = \frac{I_\theta - DF}{FF - DF}$$

Tomography



2D sample

Projection image T_θ

Sinogram

no. of projections n with resolution d of object with size R

$$n = \frac{\pi R}{2d}$$

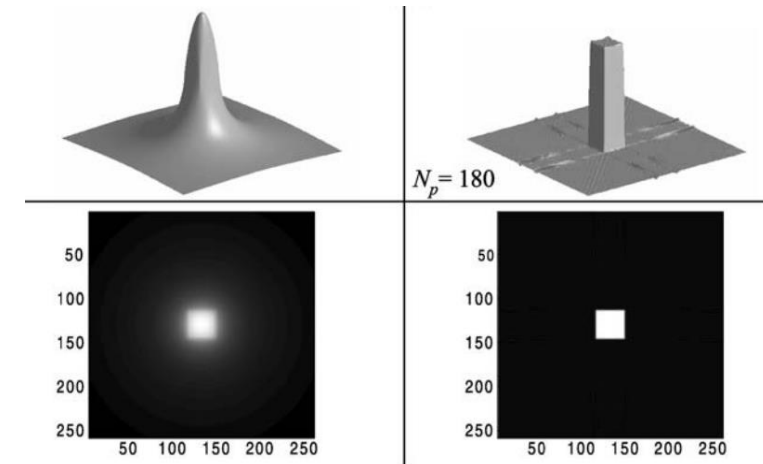
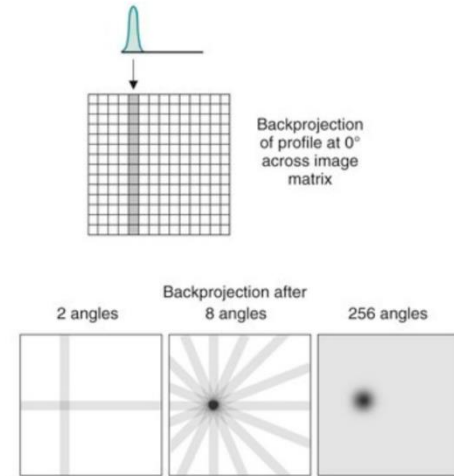
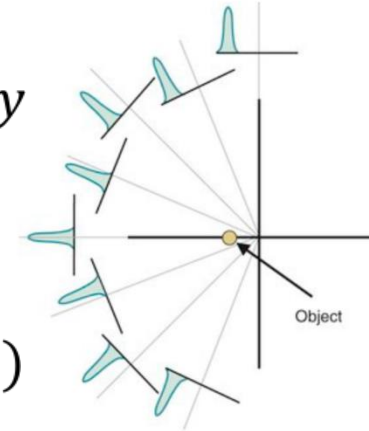
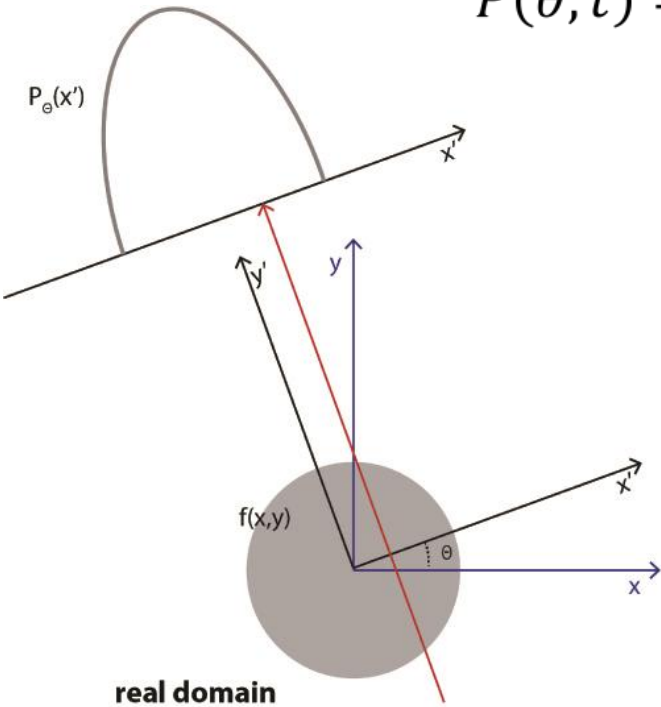
Tomographic reconstruction – Radon transform

$$P(\theta, t) = \iint f(x, y) \delta_D(x \cos \theta + y \sin \theta - t) dx dy$$

$$f'(x, y) = \frac{1}{n} \sum_{i=1}^n P(\theta_i, x \cos \theta_i + y \sin \theta_i)$$

$$\hat{P}(\theta_i, \omega) = \int P(\theta_i, \omega) e^{-i2\pi\omega t} dt$$

$$P_f(\theta_i, \omega) = \int \hat{P}(\theta_i, \omega) e^{-i2\pi\omega t} |\omega| d\omega$$

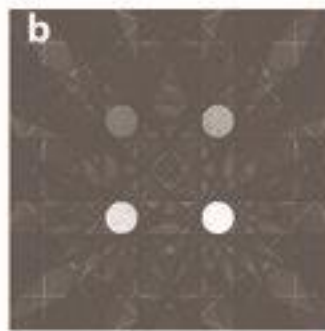


Principle for tomographic reconstruction

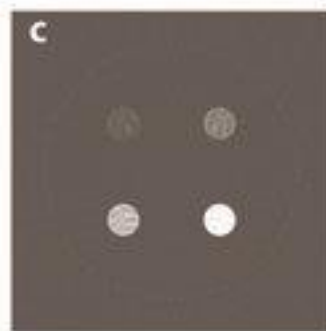
1. Collect projections, $P_\theta(x')$, for several angles
2. Calculate the Fourier transform of each projection
3. Apply the Fourier filter to approximate the ideal case
4. Find the inverse Fourier transformation of the filtered projection
5. Sum over all angles to make the reconstruction



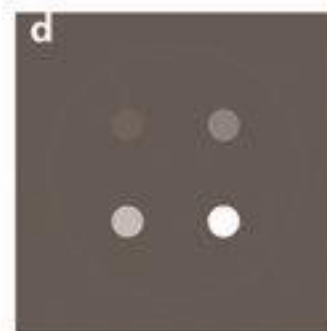
4 projections



8 projections



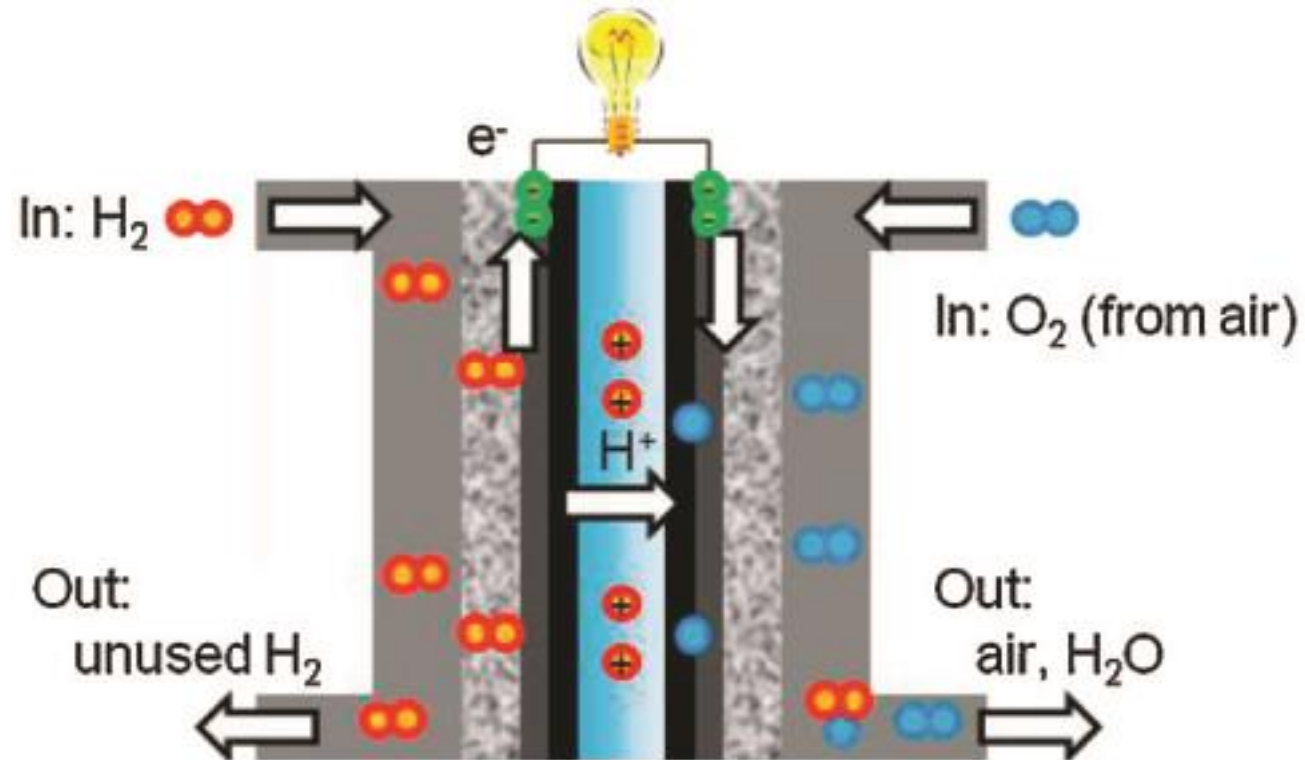
32 projections



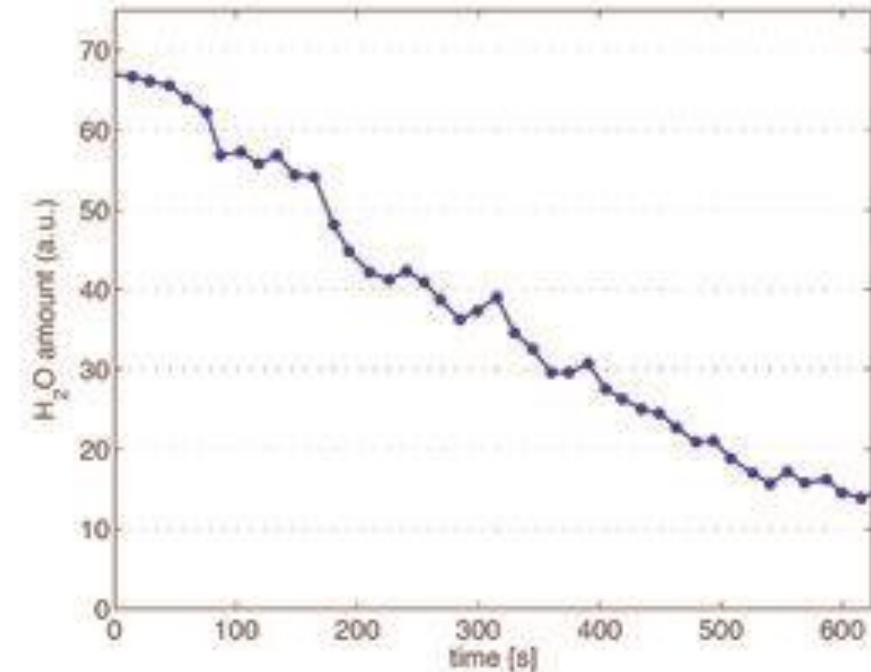
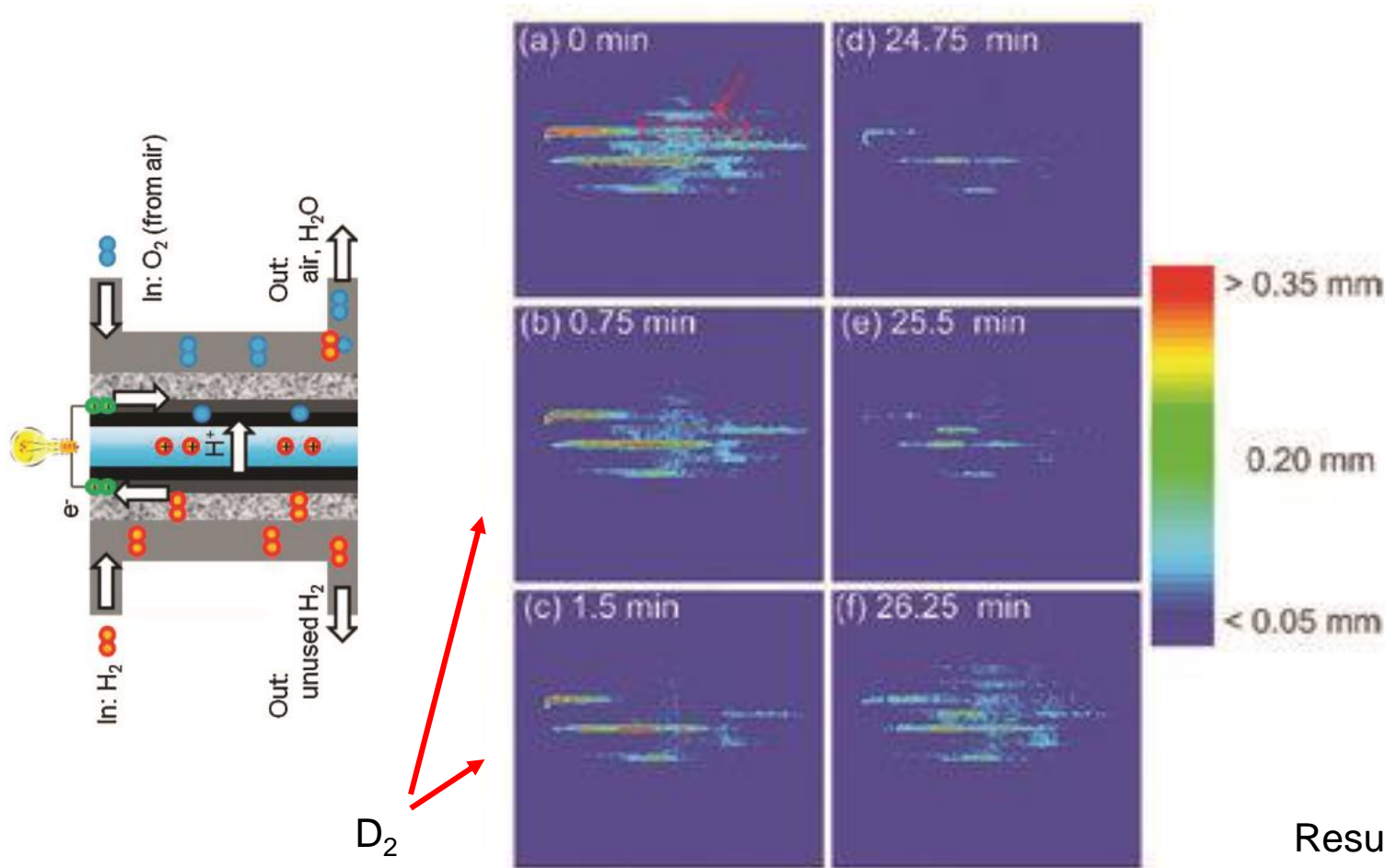
128 projections

Cases:

Polymer Electrolyte Membrane Fuel Cell (PEMFC)

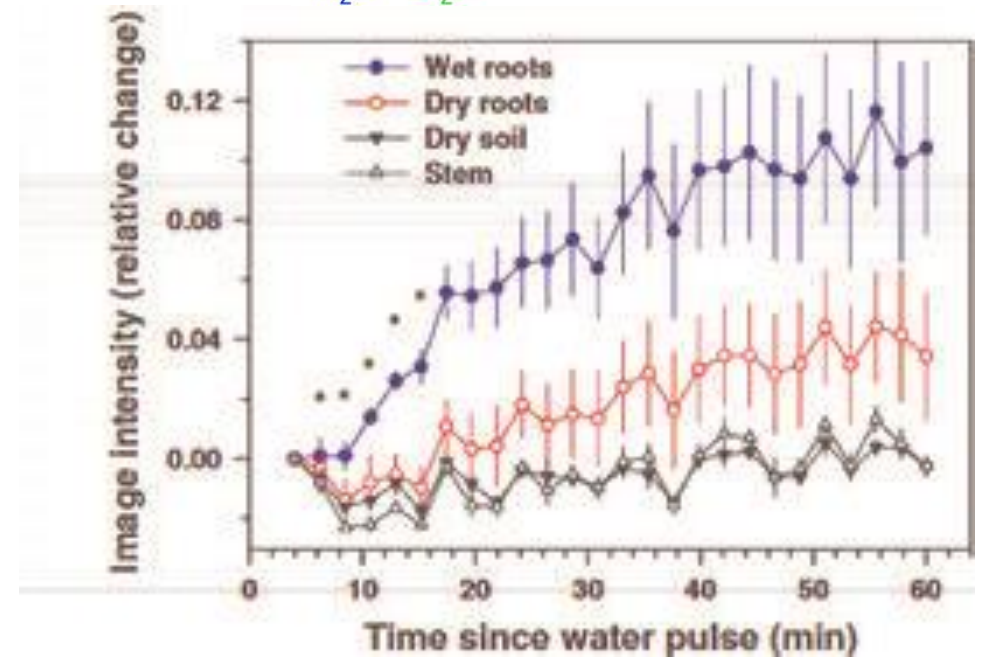
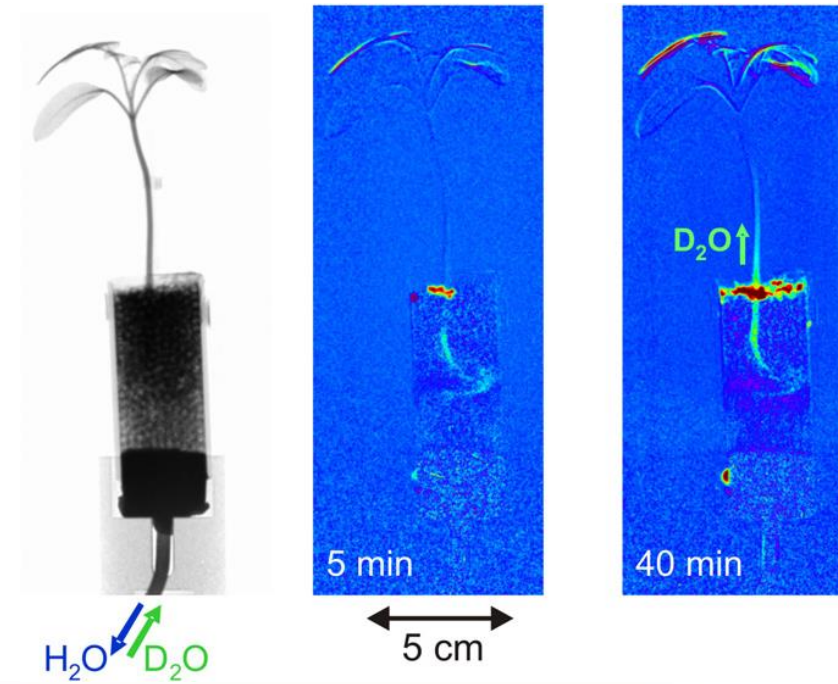
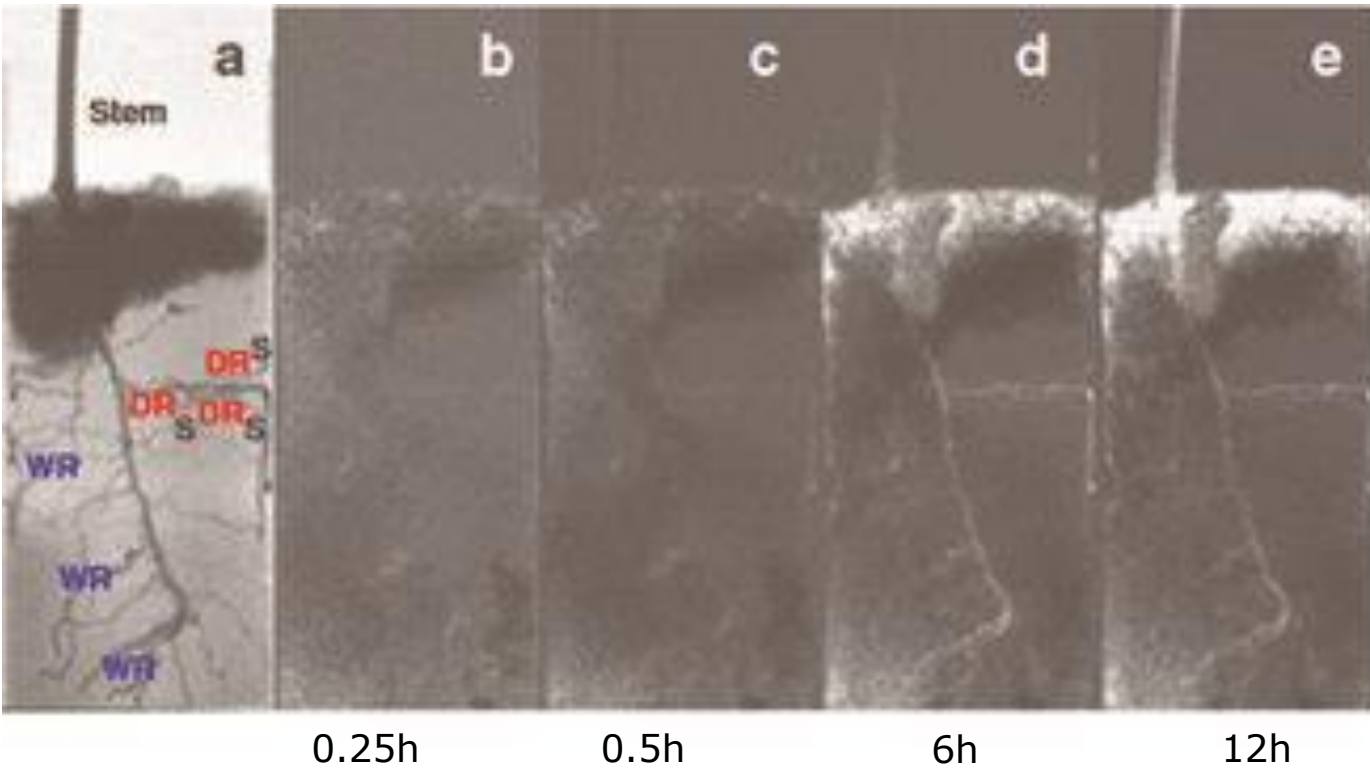


Cases: In-situ study of water in PEMFC



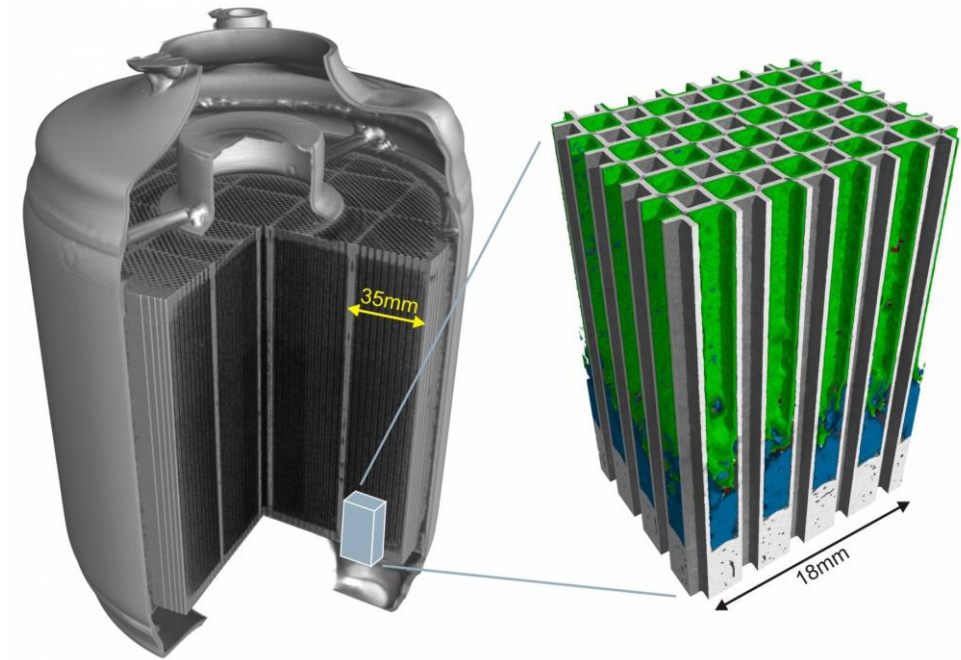
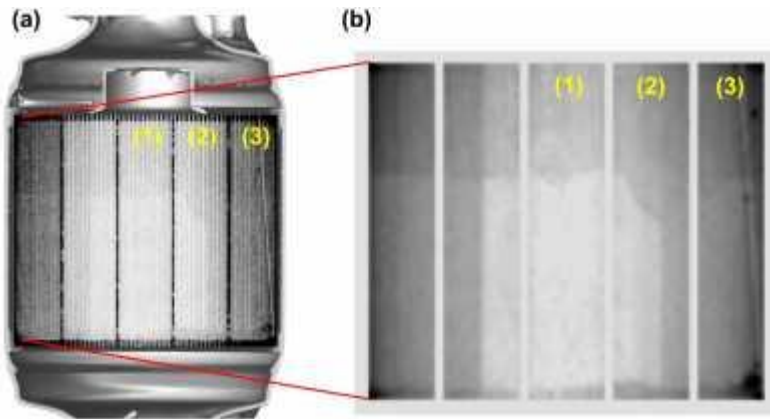
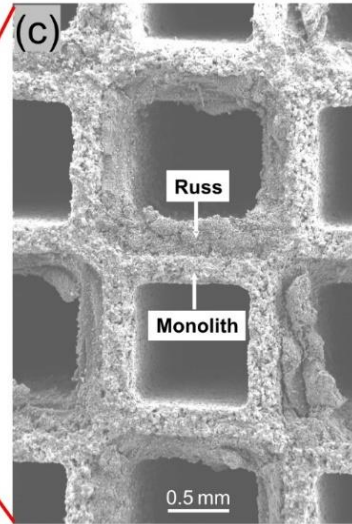
Result: a new model for two-phase flow

Cases: water uptake in plants



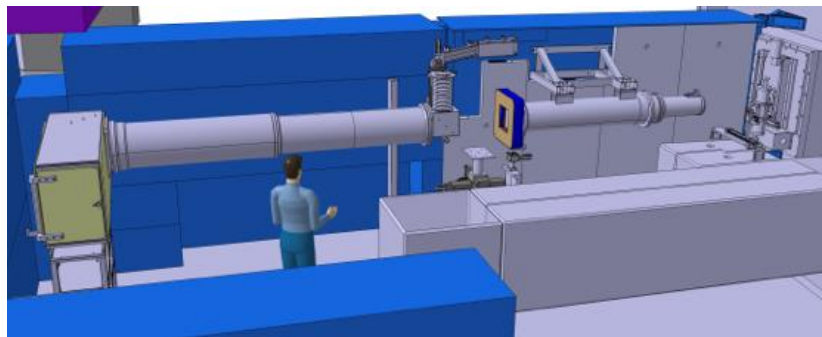
Strobl, M. et al. (2009). *J. Phys. D: Appl. Phys.* **42**, 243001.

Cases: Soot in particulate filter for diesel engine

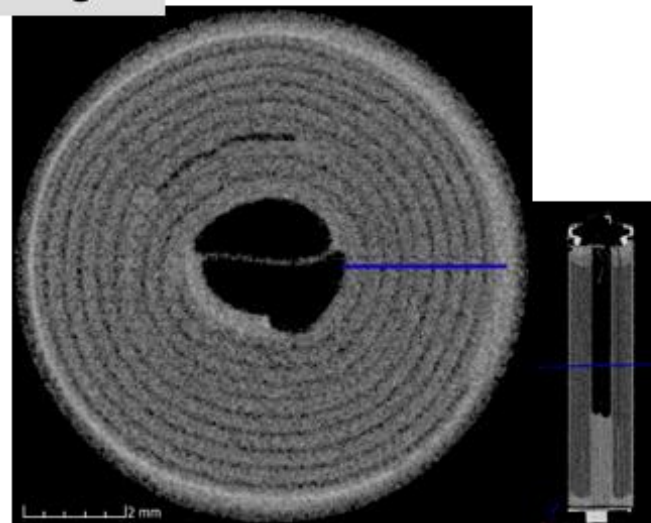


<https://www.psi.ch/media/distribution-of-soot-particles-in-particulate-filters-of-diesel-vehicles>

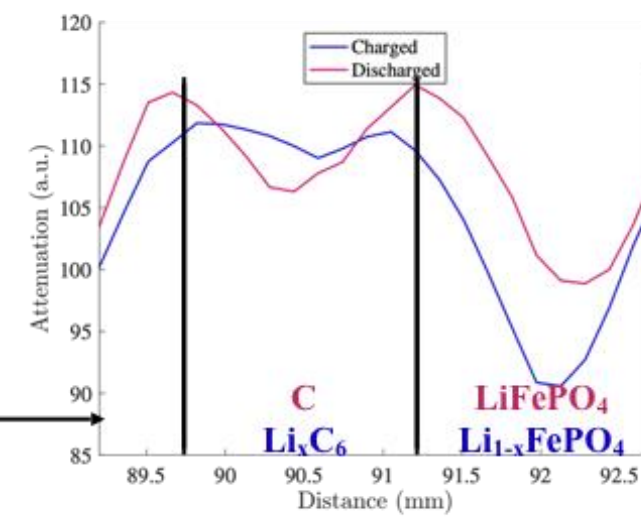
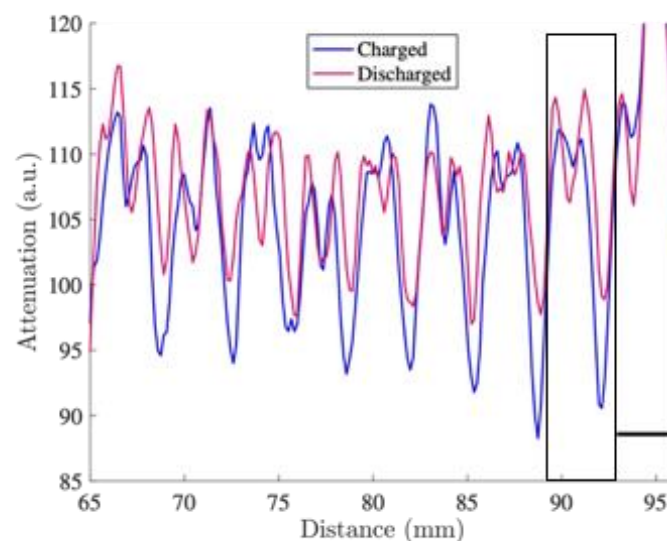
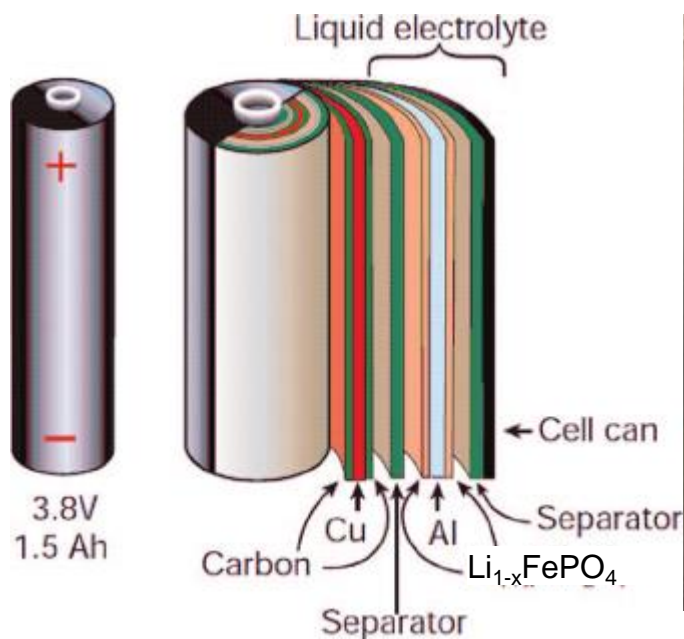
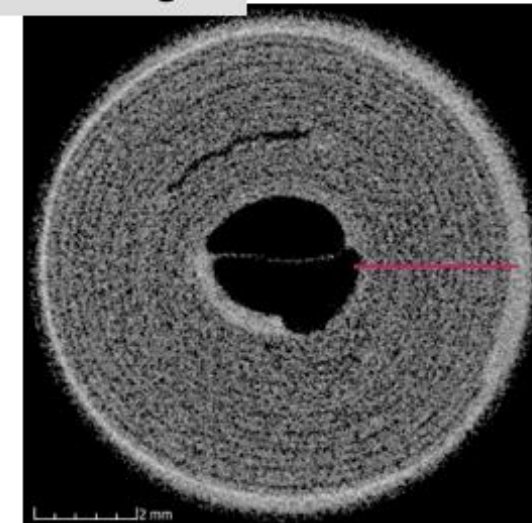
NEUTRA@PSI



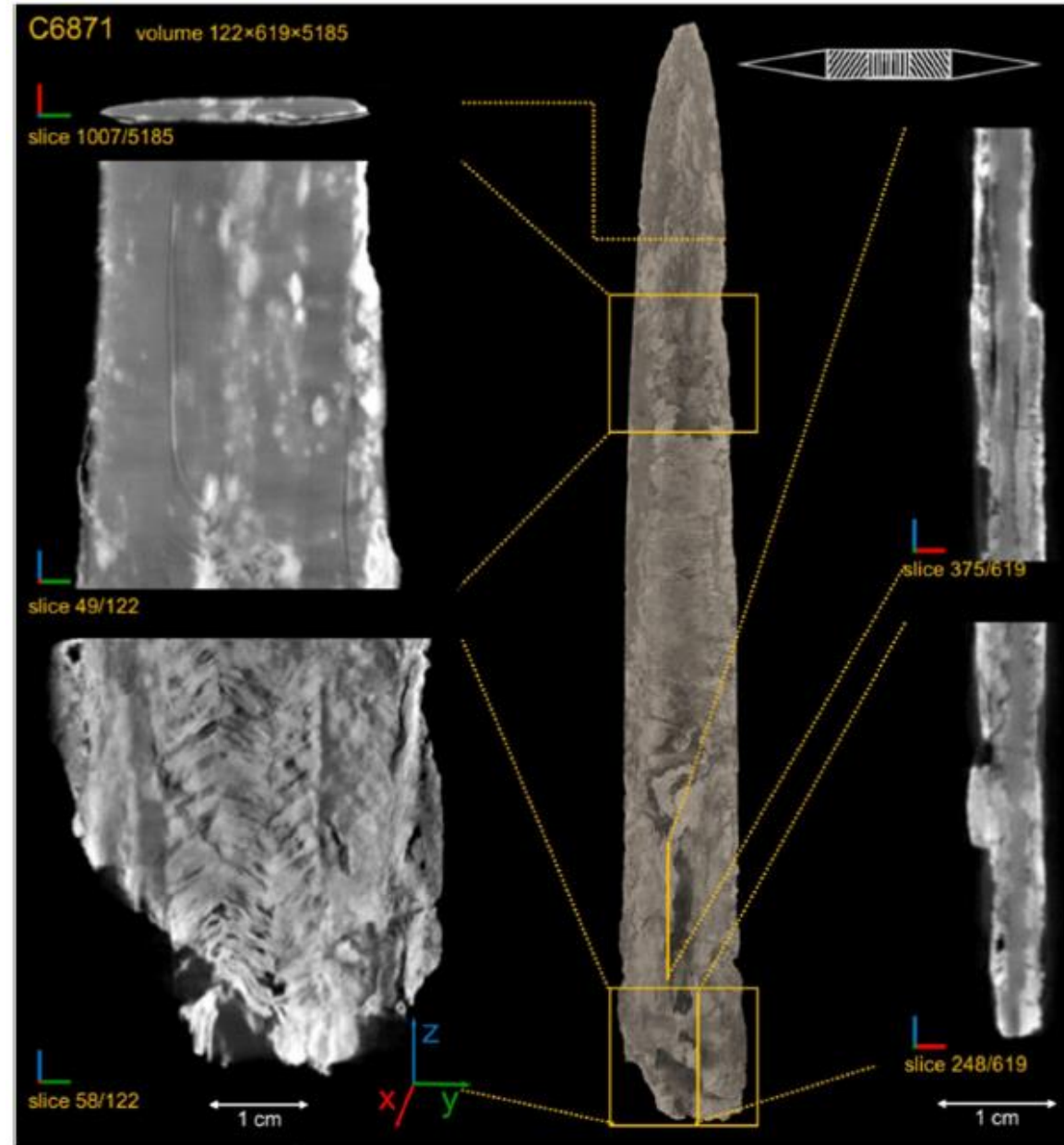
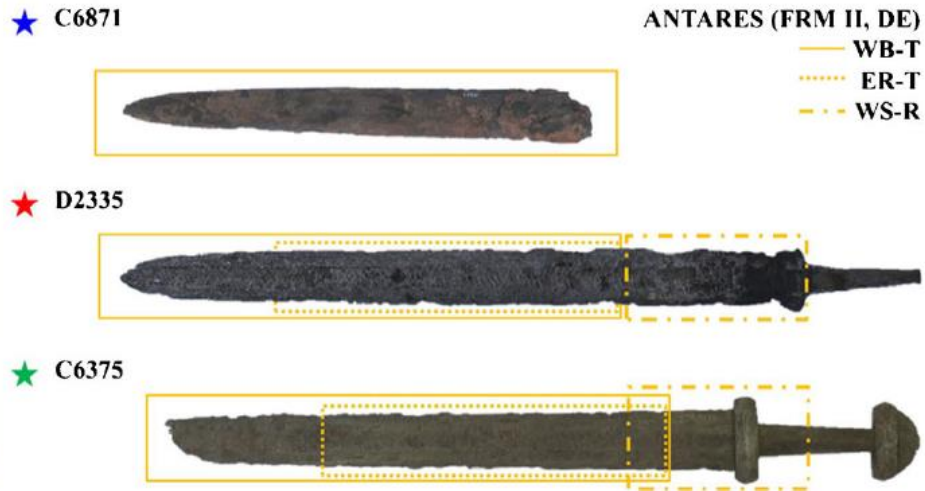
Charged



Discharged



Cases: Cultural heritage



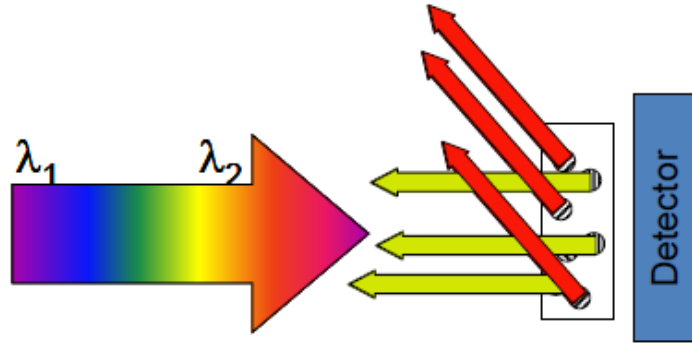
A. Fedrigo et al, Archaeol Anthropol Sci (2018) 10:1249–1263

Break – 10 min



Energy-resolved neutron imaging

Bragg-edge imaging

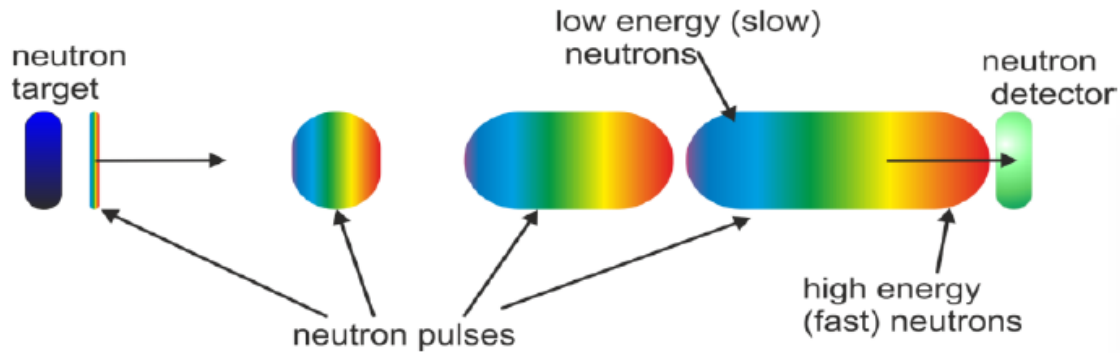


$$2d_{hkl} \sin \theta = \lambda$$

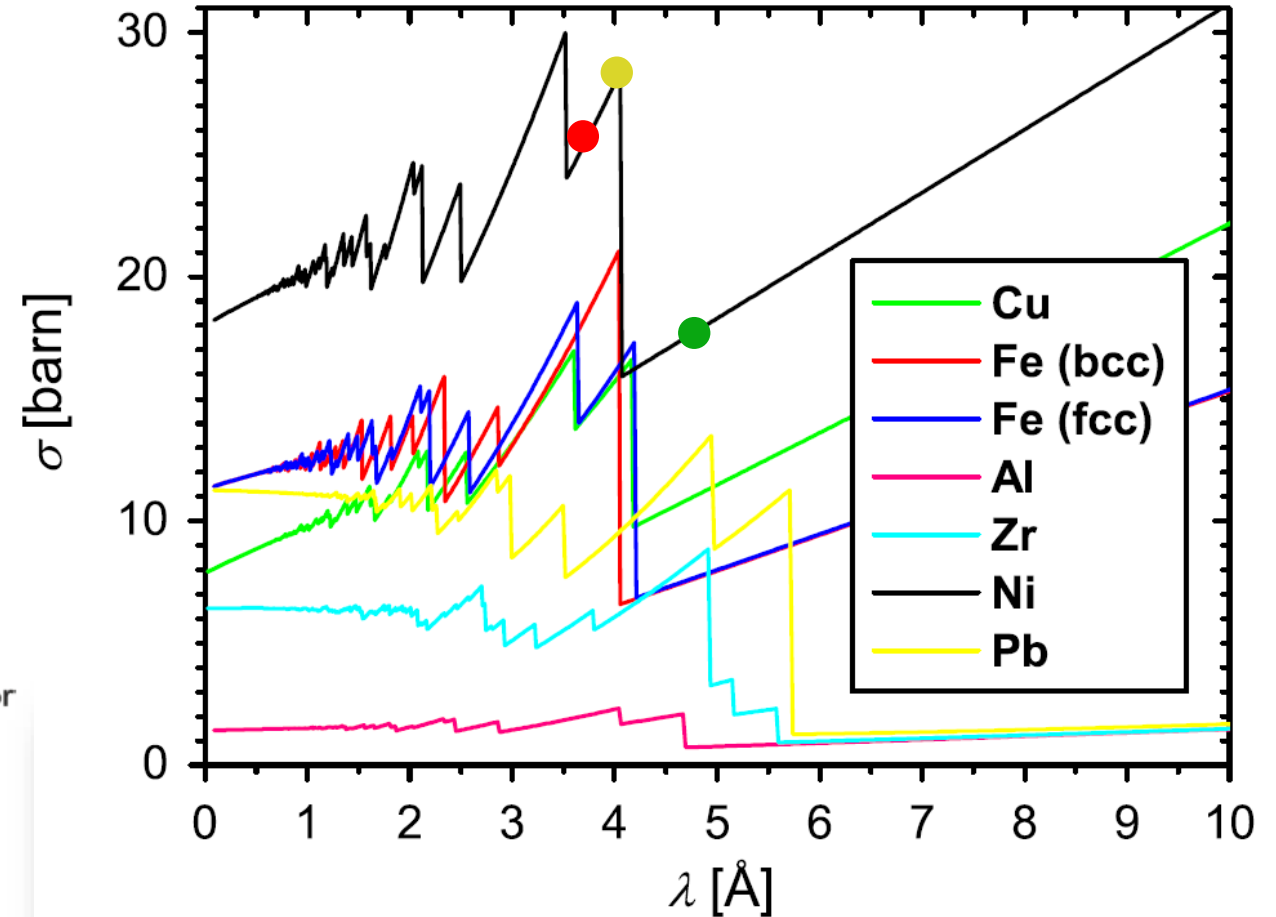
Bragg's law:

$$2d_{hkl} \sin 90^\circ = \lambda$$

$$2d_{hkl} \sin \theta < \lambda$$



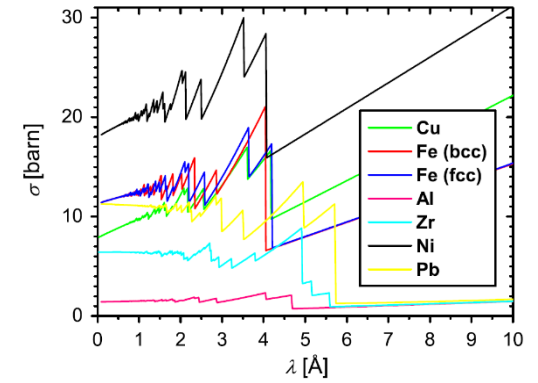
Total neutron cross section for different polycrystalline materials



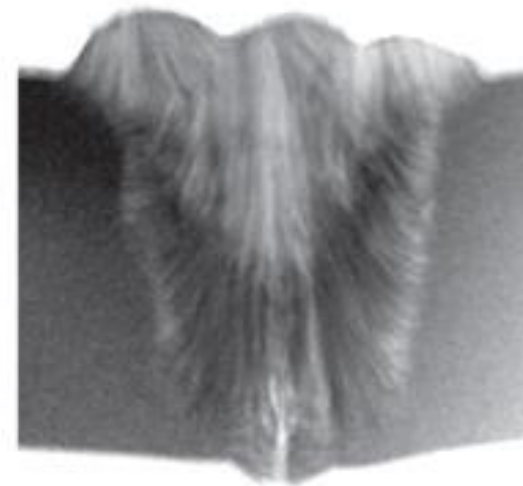
Josic, L. et al (2011). *Nucl. Instruments Methods Phys. Res.* **651**, 166.

Energy-resolved neutron imaging

Case: welding of steel



3.4 Å

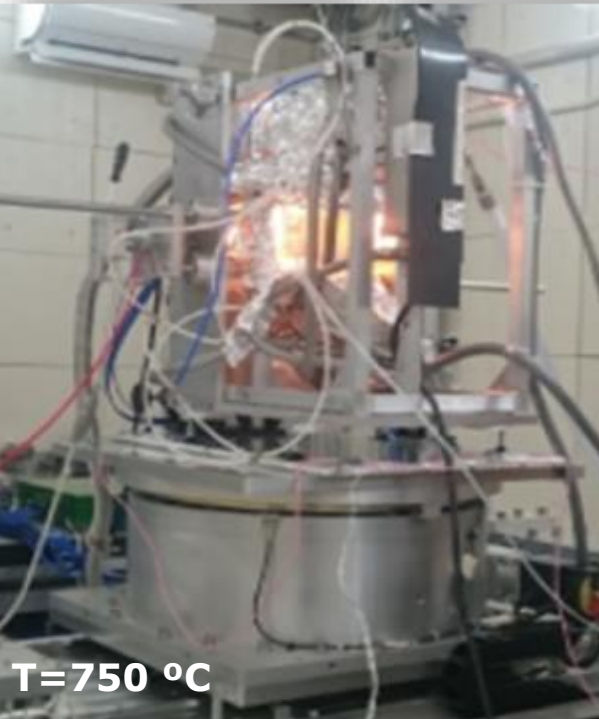


4.0 Å

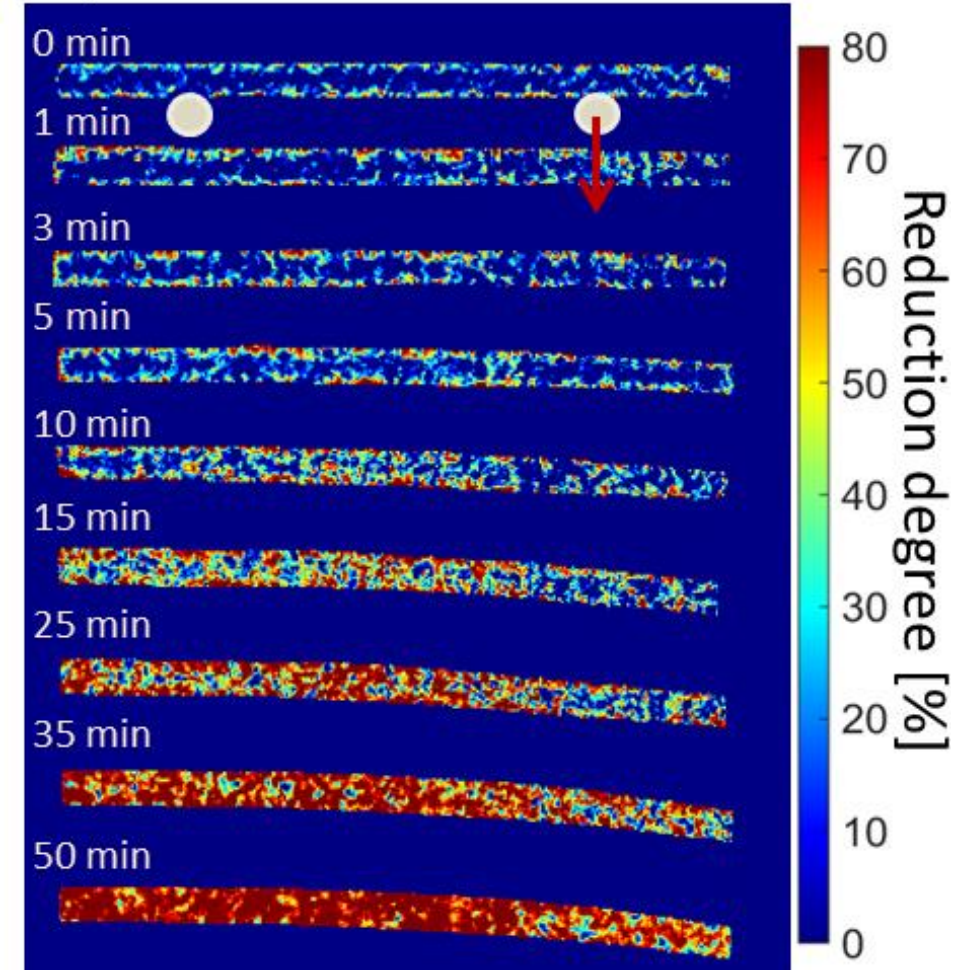
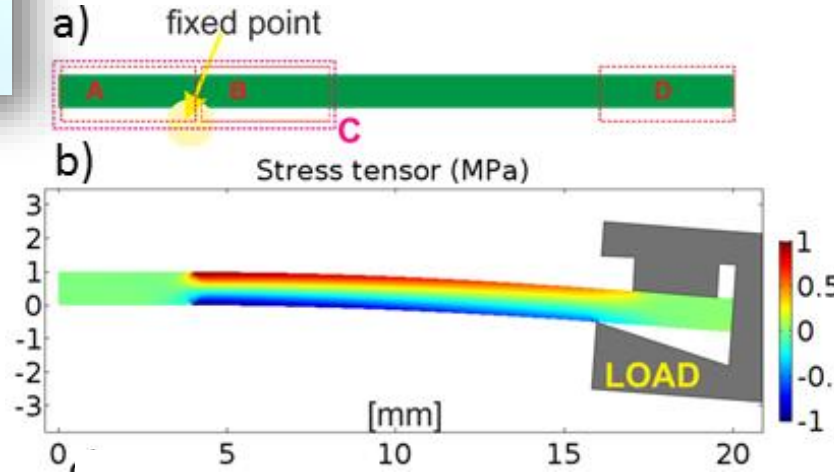


4.4 Å

Cases: In-situ Bragg-edge imaging linking strain and NiO reduction in Solid Oxide Fuel/ Electrolysis Cell electrodes



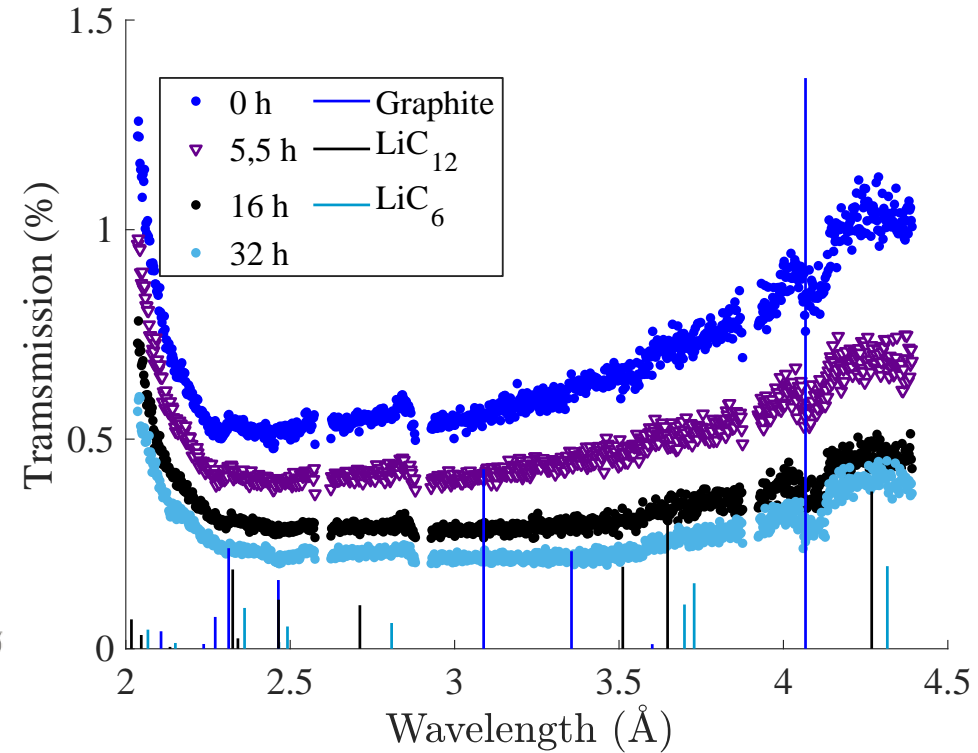
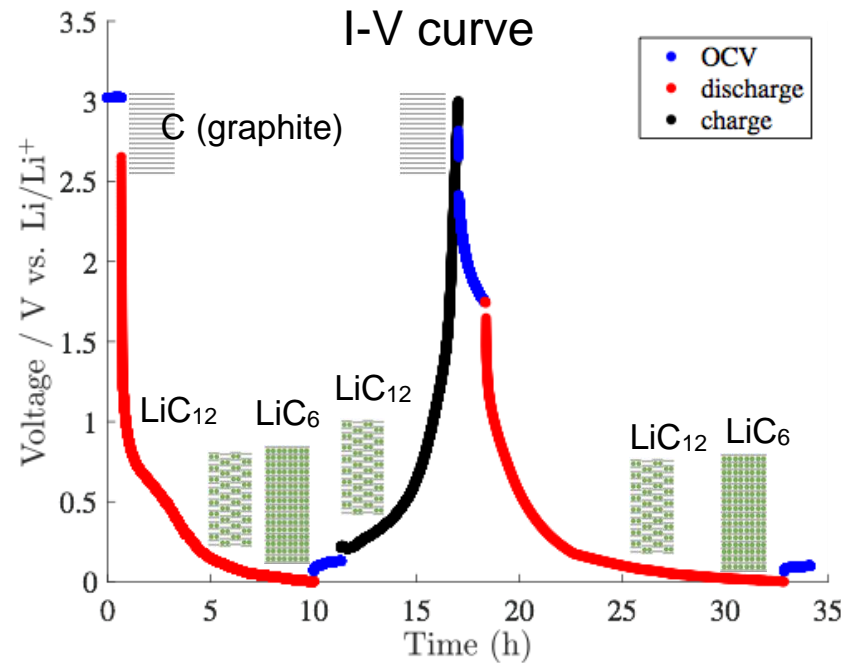
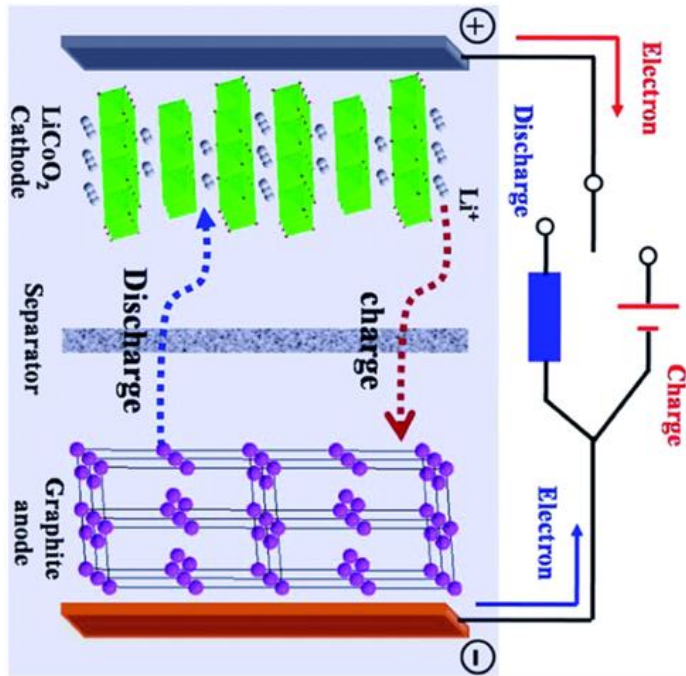
T=750 °C



M. Makowska et al, *J.Appl.Cryst.* **48**, 401(2015)

M. Makowska et al, *J. Appl. Cryst.* **49**, 1674 (2016)

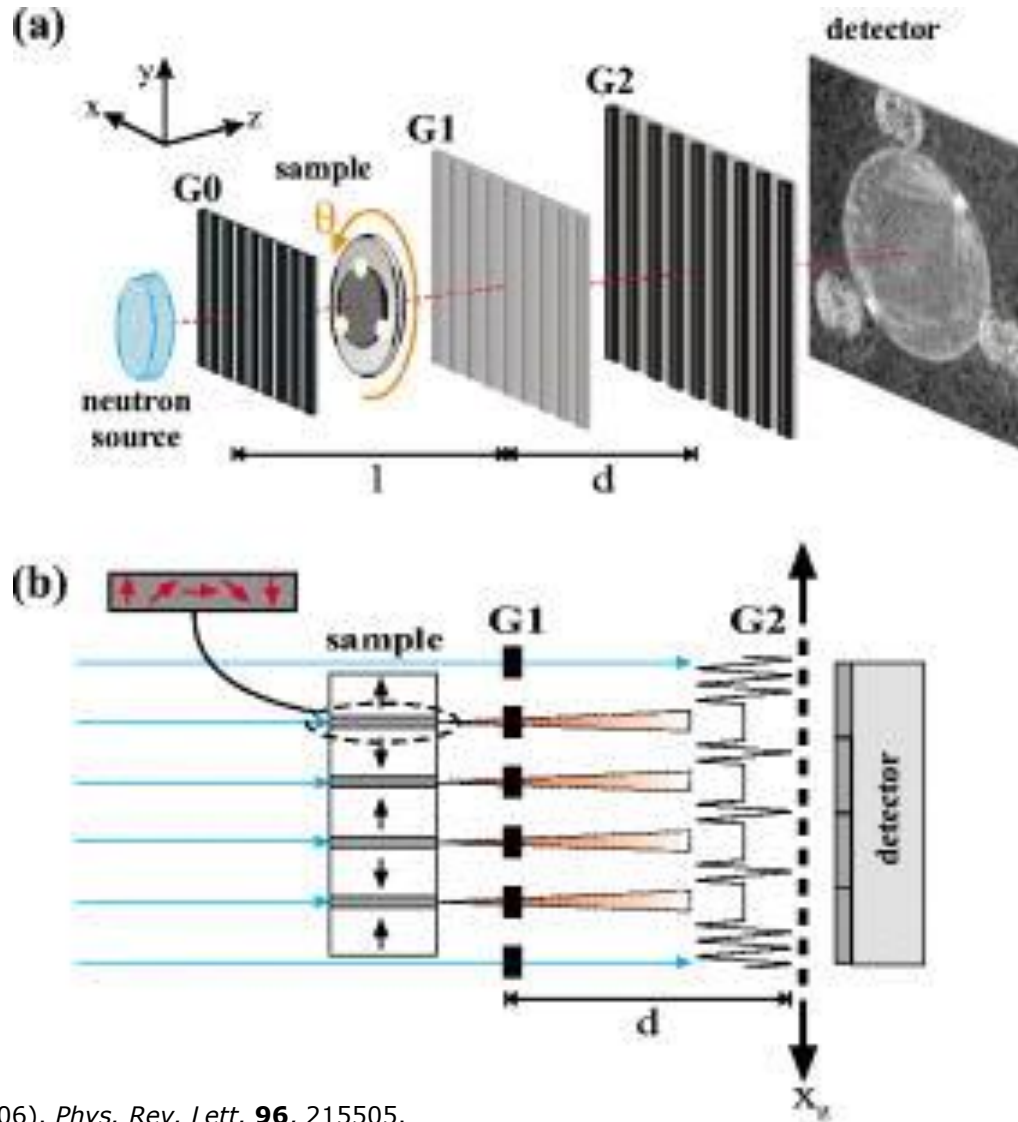
Cases: Discharge – charge of model Li-ion battery



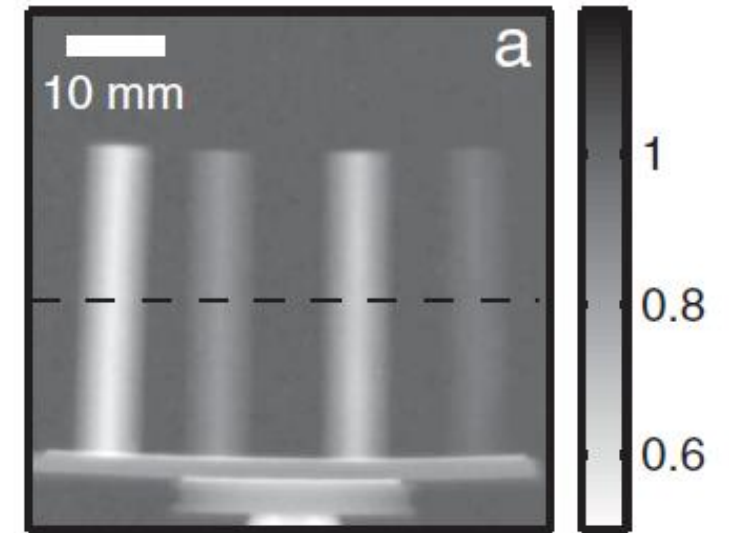
Counter Electrode, Li

Working Electrode, Graphite pellet

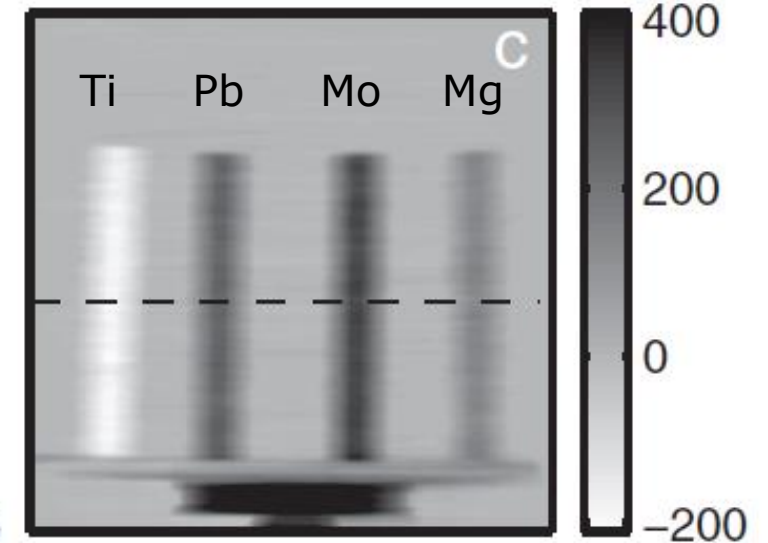
Neutron grating interferometry



object transmission a



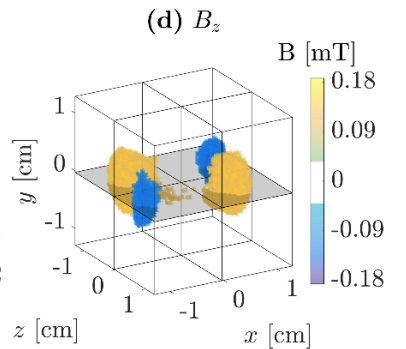
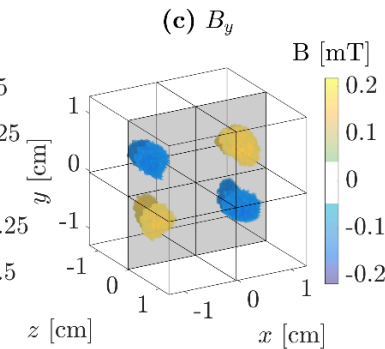
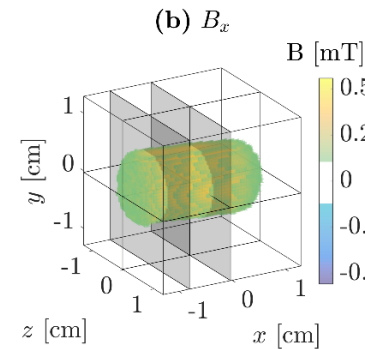
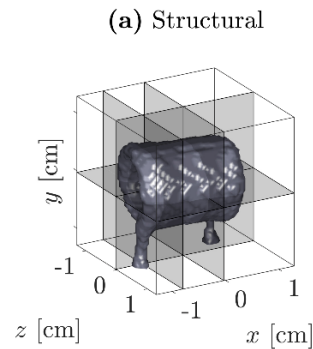
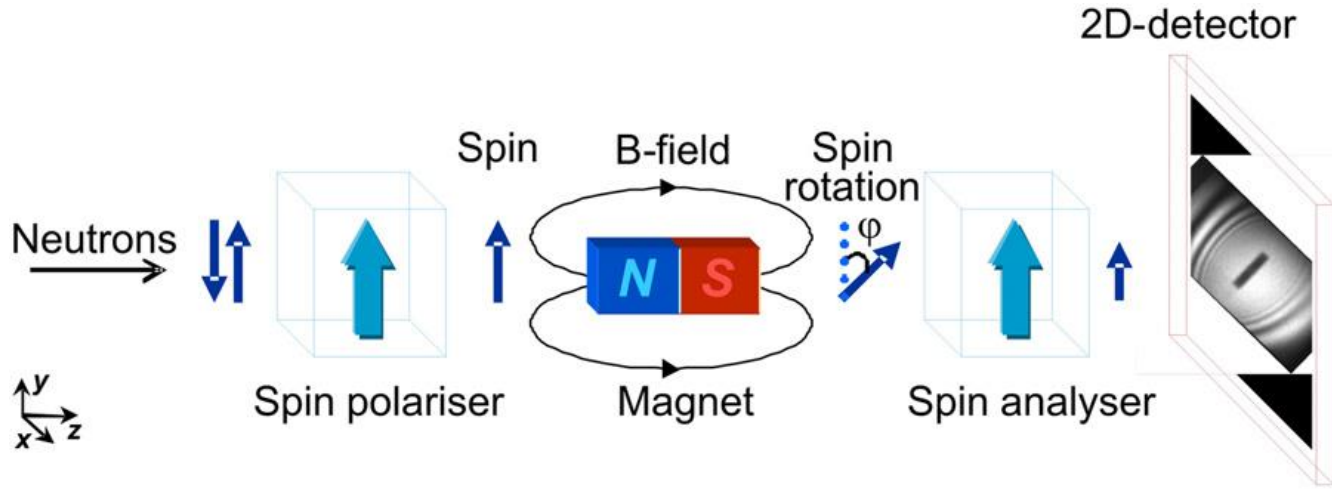
object phase shift Φ [π]



Grünzweig, C. et al. (2006). *Phys. Rev. Lett.* **96**, 215505.

Grünzweig, C. et al. (2008). *Appl. Phys. Lett.* **93**, 112504.

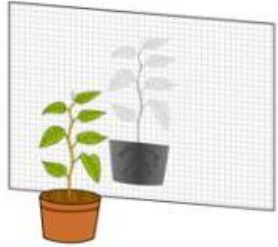
3D polarimetric neutron tomography of magnetic fields and current distributions



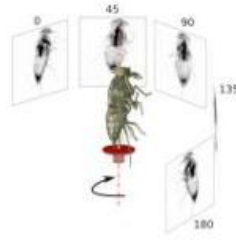
M. Sales et al, Scientific Reports, vol: 8, issue: 1, pages: 1-6, 2018

Summary

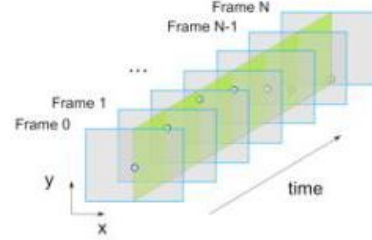
Standard techniques



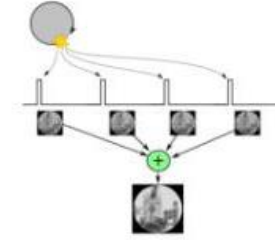
Radiography



Computed tomography

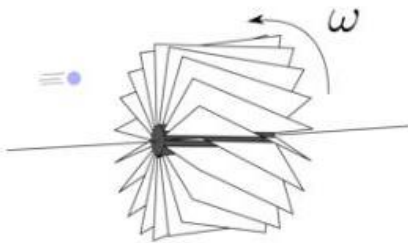


Time-series imaging

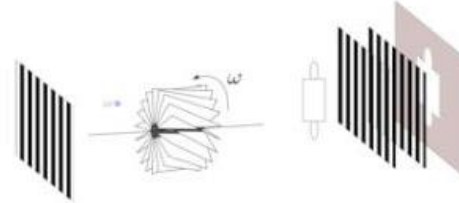


Stroboscopic imaging

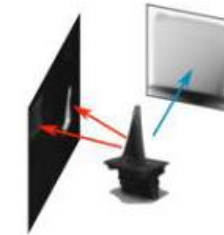
Advanced techniques



Energy selective imaging

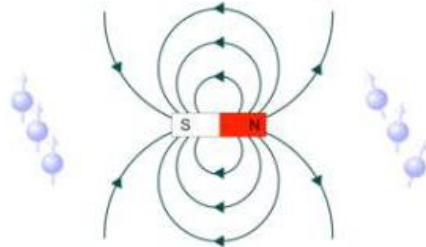


Neutron grating interferometry



Diffraction imaging

Under development



Imaging with polarized neutrons



High resolution imaging

Lehmann, E. et al. (2017). *Phys. Proc.* **88**, 5.

Learning objectives

A student who has successfully completed this module should be able to:

- Describe how the image and contrast is formed during neutron imaging and how it differs from X-ray imaging
- Explain the contributions to the neutron attenuation, and explain the relationship between the attenuation coefficient and the scattering cross section
- Explain the principles behind various types of neutron imaging methodologies
- Decide which combination of pinhole diameter, pinhole-sample distance, and sample-detector distance gives the best spatial resolution for a given experimental setup

Learning objectives

A student who has successfully completed this module should be able to:

- Decide which of the experimental parameters pinhole diameter, pinhole-sample distance, and sample-detector distance you should modify to reduce the blur at a given neutron flux and divergence
- Evaluate the quality of a tomographic reconstruction by applying the filtered back-projection algorithm
- Evaluate the advantages of neutron radiography compared to neutron tomography
- Give design principles for a neutron imaging setup for 2D and 3D analysis of a given type of sample

Acknowledgments



DanScatt



E. Mejdal Lauridsen

DTU Energy
Department of Energy Conversion and Storage

M. Makowska (now PSI), M. Lacatusu, R.E. Johnsen,
H. Lund Frandsen, L. Nilausen Cleemann
S. Koch, J. Johnson



T. Shinohara, R. Kiyonagi



N. Kardjilov



R. Woracek



P. Sittner, P. Tung, N. Elewa



M. Strobl
M. Morgano



S. Kabra, W. Kockelmann



A. Tremsin

